# Monads, Indexes and Transformations* 

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CS/E 92-017
October 12, 1992


#### Abstract

The specification and derivation of substitution for the de Bruijn representation of $\lambda$ terms is used to illustrate programming with a function-sequence monad. The resulting program is improved by automatable program transformation methods into an efficient implementation that uses primitive machine arithmetic. These transformations illustrate new techniques that assist the discovery of the arithmetic structure of the solution.


## Introduction

Substitution is one of many problems in computer science that, once understood in one context, is understood in all contexts. Why, then, must a different substitution function be written for every abstract syntax implemented? This paper shows how to specify substitution once and use the monadic structure of the specification to instantiate it on different abstract syntax structures. It also shows how to automatically derive an efficient implementation of substitution from this very abstract specification.

Formal methods that support reasoning about free algebras from first principles based on their inductive structure are theoretically attractive because they have simple and expressive

[^0]$u$ within the scope of $v$ in (2) are decremented in (3) because the $\lambda$ binding $v$ was removed in the contraction.

One way to characterize substitution with the de Bruign representation is by a series of functions, each to be applied in a different context. The first context is the body of the contracted $\lambda$. Here all references to the index 0 are to be replaced by the argument $\lambda .01$ while all references to global variables are to be decremented:

$$
\begin{aligned}
\sigma_{0} 0 & =\lambda .01 \\
\sigma_{0}(n+1) & =n
\end{aligned}
$$

Note that both right hand sides are terms, not simply integers ${ }^{1}$. In the second context, all occurrences of 0 remain unchanged, references to index 1 are now to the argument and references to indexes greater than 1 are global. All occurrences of free variables in the argument must be incremented. This gives:

$$
\begin{aligned}
\sigma_{1} 0 & =0 \\
\sigma_{1} 1 & =\lambda .02 \\
\sigma_{1}(n+2) & =(n+1)
\end{aligned}
$$

In this case, these are the only substitutions needed, but in general any number may be required. The key to this development is to calculate this sequence of functions and then use a generic recursion scheme, such as that provided by the map function, that has been specialized to select the function from the family appropriate to the context.

The first thing to observe about the sequence is that its general shape is:

$$
\begin{aligned}
\sigma_{i+1} 0 & =0 \\
\sigma_{i+1}(n+1) & \approx \sigma_{i} n
\end{aligned}
$$

To make it exact it is necessary to increment all global variables in $\sigma_{i} n$ without incrementing the local variables. This is done by another sequence of functions:

$$
\begin{aligned}
f_{0} n & =n+1 \\
f_{1} 0 & =0 \\
f_{1}(n+1) & =n+2 \\
f_{2} 0 & =0 \\
f_{2} 1 & =1 \\
f_{2}(n+2) & =n+3
\end{aligned}
$$

Observe that in the example a single application of $f_{1}$ to the body of $\sigma_{1} 1$ accounts for $\lambda .01$ being adjusted to $\lambda .02$. In general the $f_{i}$ are generated by:

$$
\begin{aligned}
f_{i+1} 0 & =0 \\
f_{i+1}(n+1) & =\left(f_{i} n\right)+1
\end{aligned}
$$

[^1]

Figure 1: Tree representations of $\lambda u \cdot(\lambda v \cdot u v(\lambda w \cdot u v w))(\lambda z, z u)$.





Figure 2: Representations of the contracted term.

So, assuming a map that applies a family of functions, the family of substitution functions, ( $\sigma_{0}, \sigma_{1}, \ldots$ ), is given by the initial substitution, $\sigma_{0}$, and the recurrence:

$$
\begin{aligned}
\sigma_{i+1} 0 & =0 \\
\sigma_{i+1}(n+1) & =\operatorname{map}\left(f_{0}, f_{1}, \ldots\right)\left(\sigma_{i} n\right)
\end{aligned}
$$

Given the sequence of functions, $\left(\sigma_{0}, \sigma_{1}, \ldots\right)$, mapping indexes to terms, the map function for sequences can be used to apply the sequence of substitution functions. This, however, results in terms of terms, since every variable has replaced its index by a term. This is not a problem, however, because the Term type constructor developed below is designed to be a monad; monads have a polymorphic function, mult, which performs the requisite flattening.

## 2 Monads

A monad is a concept from category theory that has been used to provide structure to semantics[7] and to specifications[10]. In the computer science setting a monad is defined by a parametric data type constructor, $T$, and three polymorphic functions:

$$
\begin{aligned}
\text { map } & :(\alpha \rightarrow \beta) \rightarrow T \alpha \rightarrow T \beta \\
\text { unit } & : \alpha \rightarrow T \alpha \\
\text { mult } & : T T \alpha \rightarrow T \alpha
\end{aligned}
$$

The map function is required to satisfy:

$$
\begin{aligned}
\text { map } i d_{\alpha} & =i d_{T \alpha} \\
\operatorname{map}(f \circ g) & =\text { map } f \circ \text { map } g
\end{aligned}
$$

The polymorphic functions unit and mult must satisfy:

$$
\begin{aligned}
\text { mult }_{\alpha} \circ \text { unit }_{T \alpha} & =i d_{T \alpha} \\
\text { mult }_{\alpha} \circ\left(\text { map unit }_{\alpha}\right) & =i d_{T \alpha} \\
\text { mult }_{\alpha} \circ \text { mult }_{T \alpha} & =\text { mult }_{\alpha} \circ\left(\text { map mult }_{\alpha}\right)
\end{aligned}
$$

A simple example of a monad is list. For lists, map is the familiar mapcar function of Lisp, unit is the function that produces a singleton list, and mult is the concatenate function that flattens a list of lists into a single list. Other examples of monads are given by Wadler[10].

Several categorical concepts are implicit above. The functional programming category has types as objects and (computable) functions as arrows. (Values are viewed as constant functions-arrows from the one element type.) The requirements on map specify that the type constructor $T$ and the map function together define a functor. The polymorphic types of unit and mult implicitly require them to be natural transformations. The three laws given for them are the monad laws.

Monads have been used to structure specifications (and semantics) because it is often possible to characterize interesting facets of a specification as a monad. Algorithms to exploit the particular facet may frequently be expressed in terms of the map, unit and mult functions with no explicit details of the type constructors. Finally, the many facets are brought together by composing the type constructors.

## 3 The term monad

The development in Section 1 suggests that the specification of the substitution operation will be straightforward in a monadic data type with an appropriate map. To be monadic, the data type must be parametric. The following simple type declaration is sufficient $t^{2}$ :

$$
\begin{aligned}
& \text { datatype } \operatorname{Term}(\alpha)= \operatorname{Var}(\alpha) \\
& \operatorname{Abs}(\operatorname{Term}(\alpha)) \\
& \operatorname{App}(\operatorname{Term}(\alpha) * \operatorname{Term}(\alpha))
\end{aligned}
$$

Using techniques developed in earlier work, it is possible to automatically generate map, mult and unit functions for this type realizing a monadic structure[5]. Unfortunately, the map function obtained with those techniques does not work with families of functions.

To accommodate the function sequences a new category, FunSeq, is used. The objects are data types, as before, but the morphisms are sequences of functions (formally $\operatorname{Hom}(A, B)=$ $\left.\left(B^{A}\right)^{\omega}\right)$. Identities are constant sequences of identities from the underlying category; composition is pointwise, i.e. $\left(f_{i}\right)_{i \in \omega} \circ\left(g_{i}\right)_{i \in \omega}=\left(f_{i} \circ g_{i}\right)_{i \in \omega}$.

The map function for Term exploits the new structure by shifting the series of functions whenever it enters a new context. Its definition is given as a functional program:

$$
\begin{aligned}
\operatorname{map}\left(f_{0}, f_{1}, \ldots\right)(\operatorname{Var} x) & =\operatorname{Var}\left(\left(f_{0}, f_{1}, \ldots\right) x\right) \\
\operatorname{map}\left(f_{0}, f_{1}, \ldots\right)(\operatorname{Abs} t) & =\operatorname{Abs}\left(\operatorname{map}\left(f_{1}, f_{2}, \ldots\right) t\right) \\
\operatorname{map}\left(f_{0}, f_{1}, \ldots\right)\left(\operatorname{App}\left(t, t^{\prime}\right)\right) & =\operatorname{App}\left(\operatorname{map}\left(f_{0}, f_{1}, \ldots\right) t, \operatorname{map}\left(f_{0}, f_{1}, \ldots\right) t^{\prime}\right)
\end{aligned}
$$

It is easily verified that (Term, map) satisfy the categorical definition of a functor.
Looking at these definitions, it is clear how to insert an ordinary function or value into the category, and it is straightforward to insert the families of functions needed for the example by giving the initial element of the sequence and the functional that generates all others. However, it is also necessary to define the mapping that pulls a computation from FunSeq back into the category of functional programs. This is accomplished by simply taking the first element of the function sequence. Thus, one way to realize the map function of FunSeq in a functional programming setting is with the map_with_policy function introduced in Hook, Kieburtz and Sheard[5]:

$$
\begin{aligned}
\text { map_with_policy } Z f(\text { Var } x) & = \\
\text { map_with_policy } Z f(\text { Abst }) & =\operatorname{Abs}(f x) \\
\text { map_with_policy } Z f\left(\operatorname{App}\left(t, t^{\prime}\right)\right) & =\operatorname{App}(\text { map_with_policy } Z(Z f) t) \\
& \text { map_with_policy } Z f t, \\
&
\end{aligned}
$$

[^2]```
fun apply_substitution \(\sigma_{0} M\)
    \(=\) let fun succ \(x=x+1\)
        fun transform_index \(f\)
            \(=\lambda n\). if \(n=0\) then \(n\) else \(1+f(n-1)\)
            fun transform_substitution \(\sigma\)
            \(=\lambda n\). if \(n=0\) then unit 0
                else map_with_policy transform_index succ \((\sigma(n-1))\)
    in mult(map_with_policy transform_substitution \(\sigma_{0} M\) )
    end
```

Figure 3: Substitution function

In this encoding $Z$ is the functional that generates the sequence and $f$ is the seed value. That is,

$$
\left(\operatorname{map}\left(f, Z f, Z^{2} f, \ldots\right)\right)_{0}=\text { map_with_policy } Z f
$$

Note the projection of the first element from the family of functions on the left hand side indicated by the subscript 0 .

The name map_with_policy refers to the notion of policy function introduced by Kieburtz[6, 5]. It refers to a type-specific function, such as $Z$ above, that is embedded into the program for a general polymorphic operator to produce a specialized, monomorphic operator using a similar control scheme.

The unit and mult functions automatically generated for Term can be lifted to FunSeq. Their definitions are:

$$
\begin{array}{ll}
\text { unit } & =\text { Var } \\
\text { mult }(\text { Var } x) & =x \\
\text { mult }(\text { Abs } t) & =\text { Abs (mult } t) \\
\text { mult }\left(\text { App }\left(t, t^{\prime}\right)\right) & =\text { App }\left(\text { mult } t, \text { mult } t^{\prime}\right)
\end{array}
$$

Simple inductions show that they satisfy the monad laws.
With these definitions in place the complete definition of substitution is given in Figure 3. Note that the algorithm makes no explicit mention of the data constructors. It only uses the information about the type implicit in the definition of map_with_policy, unit and mult.

## 4 Transformation to a first-order set of equations

To obtain a practical algorithm, the substitution function apply_substitution in Figure 3 must be made more efficient. This section shows how this transformation can be done automatically.

Program transformation systems operate on systems of first-order equations. To apply them to the specification of substitution the higher-order facets must be translated into first-order structures. A partial evaluation system is used to accomplish this.

The software allowing a complete automatic transformation is not yet written. The transformations below have been performed with the Schism partial evaluator [4] and the Astre program transformation system [1], which are not yet integrated and do not use the same language.

### 4.1 Transformation of the map_with_policy operator

The first step is to rewrite the program using the map_with_policy operator for the type Term $(\alpha)$ as a system of first-order functions. A partial evaluator such as Schism [4] can be used to specialize higher-order functions decreasing their order level. For example, consider the particular function $\sigma_{0}$ in the example in Section 1, and the call apply_substitution $\sigma_{0}$. A partial evaluator produces a program that does not contain apply_substitution in its full generality; it specializes the definition of apply_substitution for the particular constant $\sigma_{0}$. This specialization, called apply_substitution_ $\sigma_{0}$, does not have a function as an argument, so it is first-order.

Unfortunately, this technique is insufficient for processing calls of map_with_policy, which is called twice in the program in Figure 3. The specialization of map_with_policy for a particular policy function $K$ and seed function $g_{0}$ gives the following function $M w p_{-} g$ :

$$
\begin{array}{ll}
\operatorname{Mupp_{-}g(g,\operatorname {Var}(n))} & =\operatorname{Var}(g(n)) \\
\operatorname{Mwp_{-}g(g,\operatorname {Abs}(t))} & =\operatorname{Abs}(\operatorname{Mwp-g}(K g, t)) \\
\operatorname{Mwp_{-}g(g,\operatorname {App}(t,t^{\prime }))} & =\operatorname{App}\left(\operatorname{Mwp_{-}g(g,t),\operatorname {Mwp_{-}}(g,t^{\prime }))}\right.
\end{array}
$$

The function $M w p_{-} g$ has a function as an argument. But if it is specialized for a particular function $g_{0}$, the partial evaluator has to specialize the internal call $M w p_{-} g(K g, t)$; it loops on this attempt. Fortunately, the partial evaluator is able to detect this circumstance, allowing it to select another technique. The alternative technique translates the higher-order functions into a system of first-order functions. This standard encoding, which is due to Reynolds [8], is outlined below.

1. The first step constructs a data type that encodes how the higher-order arguments are manipulated and applied. In this case the functions to be encoded are $g_{0}$ and $K g$. For the constant function, $g_{0}$, a constant $C$ is introduced as a summand in the data type Func. The argument $K g$ cannot be encoded by a simple constant value because it contains $g$ as a free variable. Since $g$ is a higher-order parameter, it will already be represented by a value of type Func. Hence the new constructor, $F$, representing the application of $K$, must have type Func $\rightarrow$ Func. This gives the data type Func

$$
\begin{aligned}
\text { datatype Func } & =C \\
& \mid F(F u n c) .
\end{aligned}
$$

The introduction of the data type Func is a rediscovery of the sequence of functions $g_{0}, g_{1}, \ldots$ because it encodes each function in the family. The function $g_{0}$ is encoded by $C$, and the function $g_{3}$, for example, is encoded by $F(F(F(C)))$, which is written $F^{3}$.
2. The functions appearing as actual arguments are replaced by their encodings. The argument functions do not exist anymore-they are replaced by first-order data. In the call $M w p_{-} g\left(g_{0}, M\right), g_{0}$ is no longer a function but a first-order value, $\left\lceil g_{0}\right\rceil$, of type Func. The definition of $M w p_{-} g$ leads to the new function $M w p_{-} g^{\prime}$ :

$$
\begin{array}{ll}
M w p_{-} g^{\prime}(\lceil g\rceil, \operatorname{Var}(n)) & =\operatorname{Var}(\lceil g\rceil(n)) \\
M w g^{\prime}(\lceil g\rceil, A b s(t)) & =\operatorname{Abs}\left(\operatorname{Mwp-g} g^{\prime}(F(\lceil g\rceil), t)\right) \\
M w p_{-} g^{\prime}\left(\lceil g\rceil, A p p\left(t, t^{\prime}\right)\right) & =\operatorname{App}\left(M w p_{-} g^{\prime}(\lceil g\rceil, t), M w p_{-} g^{\prime}\left(\lceil g\rceil, t^{\prime}\right)\right)
\end{array}
$$

But since $\lceil g\rceil$ is not a function, the application $\lceil g\rceil(n)$ is nonsense.
3. To make sense of the applications of functional parameters in the orignal programs "application" functions are introduced. Specifically the function apply_g, defined below, decodes applications of the form $\lceil g\rceil(n)$.

$$
\begin{align*}
\operatorname{apply-} g(C, n) & =g_{0}(n) \\
\operatorname{apply-} g(F(\lceil g\rceil), n) & =(K \lambda n \cdot \operatorname{apply-} g(\lceil g\rceil, n))(n) . \tag{4}
\end{align*}
$$

Note that apply-g is a first-order function because its argument, $\lceil g\rceil$, is an element of the type Func. The partial evaluator unfolds the definition of the policy function $K$ to get a first-order expression of apply-g(F( $[g\rceil), n)$. The definition of $M w p_{-} g^{\prime}$ can be completed into:

$$
\begin{array}{ll}
M w p_{-} g^{\prime}(\lceil g\rceil, \operatorname{Var}(n)) & =\operatorname{Var}(\operatorname{apply}-g(\lceil g\rceil, n)) \\
M u p-g^{\prime}(\lceil g\rceil, A b s(t)) & =\operatorname{Abs}\left(M w p-g^{\prime}(F(\lceil g\rceil), t)\right) \\
M w g_{-} g^{\prime}\left(\lceil g\rceil, A p p\left(t, t^{\prime}\right)\right) & =\operatorname{App}\left(M w p_{-} g^{\prime}(\lceil g\rceil t), M w p_{-} g^{\prime}\left(\lceil g\rceil, t^{\prime}\right)\right)
\end{array}
$$

Recall that this encoding is done with respect to a specific call of map_with_policy $Z g_{0} M$. In the program in Figure 3 there are two such calls, map_with_policy transform_indexsucc( $\sigma(n-$ 1)) and map_with_policy transform_substitution $\sigma_{0} M$. If the partial evaluator succeeds in the transformation of equation (4), then the new functions corresponding to $M w p_{-} g$ and apply_g will constitute a first-order program equivalent to the functions generated by map_with_policy. This step of the transformation can be automated using a partial evaluator like Schism.

### 4.2 Application to apply_substitution

Using the preceding techniques, the function apply_substitution is successfully transformed into the first-order program in Figure 4. The data type Subst and the data type Fseq are introduced using the techniques above for the encodings of transform_index and transform_substitution.

$$
\begin{aligned}
& \text { datatype Subst }= \\
& \text { So } \\
& \text { datatype } F s e q=S U B S T(\text { Subst }) \\
&= \\
& \text { SUCC } \\
& \text { dSEQ }(\text { Fseq })
\end{aligned}
$$

```
fun apply_substitution_}\mp@subsup{\sigma}{0}{}(M
= let fun
    apply- f(SUCC, n) =s(n)
    |apply- }f(FSEQ(f),n)=\mathrm{ if }n=0\mathrm{ then 0
    else s(apply_f(f,n-1))
    fun
    Mwp_f(f,\operatorname{Var}(n))=\operatorname{Var}(\mp@subsup{\operatorname{apply-}}{-}{\prime}(f,n))
    |Mw\mp@subsup{p}{-}{\prime}f(f,Abs(t)) = Abs(Mw\mp@subsup{p}{-}{}f(FSEQ(f),t))
    |Mw\mp@subsup{p}{-}{\prime}f(f,App(t,\mp@subsup{t}{}{\prime}))=App(Mw\mp@subsup{p}{-}{}f(f,t),Mw\mp@subsup{p}{-}{}f(f,\mp@subsup{t}{}{\prime}))
    fun
    apply_\sigma(S0,n) = 的(n)
    | apply_\sigma(SUBST(\sigma),n)= if n=0 then unit(0)
                                else Mwp_f(Succ,(apply_\sigma(\sigma,n-1)))
    fun
    Mwp_\sigma(\sigma,\operatorname{Var}(n))= Var(apply_}\sigma(\sigma,n)
    | Mwp_\sigma(\sigma,Abs(t)) = Abs(Mw\mp@subsup{p}{-}{}\sigma(SUBST(\sigma),t))
    |Mw\mp@subsup{p}{-}{}\sigma(\sigma,App(t,\mp@subsup{t}{}{\prime}))=App(Mw\mp@subsup{p}{-}{}\sigma(\sigma,t),Mw\mp@subsup{p}{-}{}\sigma(\sigma,\mp@subsup{t}{}{\prime}))
    in mult(Mwp_(\sigma)(S0,M))
    end
```

Figure 4: First-order Program

These two data types are isomorphic to the data type $\mathrm{Nat}^{3}$ which can be implemented efficiently in the hardware. However, the specialized function $M w p_{-} \sigma$ does not exploit the efficient implementation since it uses the (essentially unary) representation of the data type instead. Thus, the function apply_ $\sigma$ must peel off all of the data constructors each time Mwp_ $\sigma$ is applied to $\operatorname{Var}(n)$. For example, after three levels of abstraction, $\sigma_{3}$ is represented by $\operatorname{SUBST}(\operatorname{SUBST}(S U B S T(S 0))$ ). (The same is also true of the function Mwp_f.) To eliminate this inefficiency, which was present in the calling behavior of the original specification, the data types Subst and Fseq must be changed to the uniform data type Nat. This transformation can be performed automatically by Astre. Ultimately the explicit use of Nat will facilitate the use of primitive arithmetic in the program.

## 5 Simple transformations

The following two simple transformations are performed automatically by Astre after introducing new function symbols. The first one introduces indexes to count the level of abstractions. The second replaces the composition of $M w p$ with the function mult by a single function. The order of these transformations does not matter; they can be done simultaneously.

For technical reasons recursive definitions of the form:

$$
g(n)=\text { if } n=0 \text { then } e_{1} \text { else } e_{2}
$$

are manipulated more effectively by Astre in the equivalent form:

$$
\begin{aligned}
& g(0)=e_{1}[0 / n] \\
& g(s(n))=e_{2}[s(n) / n]
\end{aligned}
$$

The notation $e\left[e^{\prime} / x\right]$ denotes the substitution of expression $e^{\prime}$ for $x$ in $e$. This restriction of the form of equations ensures the termination of the rewriting used by Astre to unfold the definition of $g$.

### 5.1 Introduction of indexes

The isomorphism between the automatically generated type Subst and the natural numbers is made explicit by introducing the function iso_ $\sigma:$ Nat $\rightarrow$ Subst:

$$
\text { fun } \begin{aligned}
\text { iso_ } \sigma(s(i)) & =\text { SUBST }(\text { iso_ } \sigma(i)) \\
\mid i s o_{-} \sigma(0) & =S 0
\end{aligned}
$$

The functions apply- $\sigma$ and $M w p_{-} \sigma$ are replaced by the new functions $\sigma(i, n)$ (for $\sigma_{i}(n)$ ) and $M w p_{-} \sigma^{\prime}$, respectively. These functions satisfy:

$$
\begin{aligned}
\text { fun } \sigma(i, n) & =\text { apply_} \sigma\left(i s o_{-} \sigma(i), n\right) \\
M w p_{-} \sigma^{\prime} & : N a t * N a t \rightarrow \text { Term }(\text { Nat }) \\
M w p_{-} \sigma^{\prime}(i, n) & =M w p_{-} \sigma\left(i s o_{-} \sigma(i), n\right)
\end{aligned}
$$

[^3]```
fun apply_substitution_ \(\sigma_{0}(M)\)
    \(=\) let fun
        \(f(0, n) \quad=s(n)\)
        \(\mid f(s(i), 0) \quad=0\)
        \(\mid f(s(i), s(n))=s(f(i, n))\)
        fun
        \(\operatorname{Mwp}_{-} f^{\prime}(i, \operatorname{Var}(n))=\operatorname{Var}(f(i, n))\)
        \(\mid M w p_{-} f^{\prime}(i, A b s(t))=A b s\left(M w p_{-} f^{\prime}(s(i), t)\right)\)
        \(\mid M u p_{-} f^{\prime}\left(i, \operatorname{App}\left(t, t^{\prime}\right)\right)=\operatorname{App}\left(M u p_{-} f^{\prime}(i, t), M w p_{-} f^{\prime}\left(i, t^{\prime}\right)\right)\)
        fun
        \(\sigma(0, n) \quad=\sigma_{0}(n)\)
        \(\mid \sigma(s(i), n) \quad=\operatorname{unit}(0)\)
        \(\mid \sigma(s(i), s(n)) \quad=M w p_{-} f^{\prime}(0, \sigma(i, n))\)
        fun
        \(\operatorname{Mwp}_{-} \sigma^{\prime}(i, \operatorname{Var}(n))=\operatorname{Var}(\sigma(i, n))\)
        \(\mid: M w p_{-} \sigma^{\prime}(i, A b s(t))=A b s\left(M w p_{-} \sigma^{\prime}(s(i), t)\right)\)
        \(\mid M w p_{-} \sigma^{\prime}\left(i, A p p\left(t, t^{\prime}\right)\right)=\operatorname{App}\left(M w p_{-} \sigma^{\prime}(i, t), M w p_{-} \sigma^{\prime}\left(i, t^{\prime}\right)\right)\)
    in \(\operatorname{mult}\left(M w p-\sigma^{\prime}(0, M)\right)\)
    end
```

Figure 5: Program with indexes

Using these new equations, the Astre system implements the data type Subst using the data type Nat. New functions to implement the data type Fseq using Nat are also provided to the Astre system which then gives the program in Figure 5. The program in Figure 5 does not improve the performance of the program in Figure 4. However, its explicit use of numbers is key to the improvements presented in the next section.

### 5.2 Composition step

The transformation continues with a simple (automatic) step that replaces the composition of mult with Mwp_ $\sigma^{\prime}$ by a single function. ${ }^{4}$ This is accomplished by introducing a function symbol, Ewp, which is equated to the composition of mult with Mwp- $\sigma^{\prime}$ :

$$
\operatorname{mult}\left(M w p-\sigma^{\prime}(0, M)\right)=E w p(0, M)
$$

[^4]```
fun apply_substitution_ \(\sigma_{0}(M)\)
\(=\) let fun
    \(f(0, n) \quad=s(n)\)
    \(\mid f(s(i), 0)=0\)
    \(\mid f(s(i), s(n))=s(f(i, n))\)
    fun
    \(\operatorname{Mwp}(i, \operatorname{Var}(n))=\operatorname{Var}(f(i, n))\)
        \(\mid \operatorname{Mwp}(i, \operatorname{Abs}(t))=\operatorname{Abs}(\operatorname{Mwp}(s(i), t))\)
        \(\mid \operatorname{Mwp}\left(i, \operatorname{App}\left(t, t^{\prime}\right)\right)=\operatorname{App}\left(M w p(i, t), M w p\left(i, t^{\prime}\right)\right)\)
        fun
        \(\sigma(0, n) \quad=\sigma_{0}(n)\)
        \(\mid \sigma(s(i), n)=\operatorname{unit}(0)\)
        \(\mid \sigma(s(i), s(n))=\operatorname{Mwp}(0, \sigma(i, n))\)
        fun
        \(\operatorname{Ewp}(i, \operatorname{Var}(n))=\sigma(i, n)\)
        \(\mid \operatorname{Ewp}(i, \operatorname{Abs}(t))=\operatorname{Abs}(\operatorname{Ewp}(s(i), t))\)
        \(\mid \operatorname{Ewp}\left(i, \operatorname{App}\left(t, t^{\prime}\right)\right)=\operatorname{App}\left(\operatorname{Ewp}(i, t), \operatorname{Ewp}\left(i, t^{\prime}\right)\right)\)
    in \(\operatorname{Ewp}(0, M))\)
    end
```

Figure 6: Composed Program

Astre gives the program in Figure 6 which uses neither mult, nor $M w p_{-} \sigma^{\prime}$ (in the figure, $M w p_{-} f^{\prime}$ has been renamed Mwp to simplify the nomenclature).

## 6 Transformation of the sequence of the $\sigma$ functions

The transformations in this section exploit the arithmetic arguments introduced above to replace then expensive and redundant recursive calculations in $\sigma$ and $E w p$ with index arithmetic.

The function $\sigma(i, n)$ of the program in Figure 6 is a rediscovery of the series of functions $\sigma_{i}(n)$ of Section 1. To further refine this program a specific instance of apply_substitution $\sigma_{0}$ must be specified. In what follows, the substitution function $\sigma_{0}$, needed for the contraction described in Section 1, is used to illustrate the specialization. Recall that $\sigma_{0}$ replaces variables of index 0 with the term $\lambda .01$, which is represented by $\operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1)))$.

$$
\begin{aligned}
& \sigma_{0}(0)=\operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1))) \\
& \sigma_{0}(s(n))=\operatorname{unit}(n)
\end{aligned}
$$

Unfolding the above equations yields a complete definition of $\sigma(i, n)$ :

$$
\begin{align*}
& \sigma(0,0)=\operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1))) \\
& \sigma(0, s(n))=\operatorname{unit}(n) \\
& \sigma(s(i), 0)=\operatorname{unit}(0) \\
& \sigma(s(i), s(n))=\operatorname{Mwp}(0, \sigma(i, n)) \tag{5}
\end{align*}
$$

Since the equational program is complete with respect to Nat $*$ Nat, the computation of any instance of $\sigma(i, n)$ results in a ground constructor term. For example, $\sigma(4,2)$ yields:

$$
\begin{align*}
& \sigma(s(s(s(s(0)))), s(s(0))) \rightarrow  \tag{6}\\
& M w p(0, \sigma(s(s(s(0))), s(0))) \rightarrow  \tag{7}\\
& M w p(0, M w p(0, \sigma(s(s(0)), 0))) \rightarrow \\
& M w p(0, M w p(0, \operatorname{Var}(0))) \rightarrow \\
& M w p(0, \operatorname{Var}(f(0,0))) \rightarrow \\
& \operatorname{Var}(f(0, f(0,0))) \rightarrow \\
& \operatorname{Var}(f(0, s(0))) \rightarrow \\
& \operatorname{Var}(s(s(0)))
\end{align*}
$$

Rewrites (6) and (7) are unfoldings by equation (5). Computation of any instance of $\sigma(i, n)$ by naturals can begin with unfoldings using equation (5) until a subterm, $\sigma(u, v)$, in which $u$ and/or $v$ are equal to 0 is obtained.

This suggests a target program of the form:

$$
\begin{aligned}
\sigma(i, n)= & \text { if } i>n \text { then } e_{1} \\
& \text { else if } i=n \text { then } e_{2} \\
& \text { else } e_{3}
\end{aligned}
$$

where $e_{1}, e_{2}$, and $e_{3}$ are expressions. The transformation will be beneficial if these expressions are efficient. This step introduces a form of function definition by a conditional (instead of structural induction) that violates the technical restriction on programs used to assure termination of rewriting as required by the Astre system. Presently, Astre does not perform this part of the transformation. Moreover, the transformation does not directly generate the conditional; instead it generates the complete definition:

$$
\begin{aligned}
& \sigma(s(i)+k, k)=u_{1} \\
& \sigma(k, k)=u_{2} \\
& \sigma(k, s(n)+k)=u_{3}
\end{aligned}
$$

### 6.1 First transformation step

The general strategy of the two transformation steps that follow is to discover arithmetic operations implicit in the recursion structure of programs. The first step in this process is a definition that makes the iteration structure of functions explicit.

Definition 1 Let $x$ be a variable of type $\alpha$, let $y_{i}$ be a term of type $\beta_{i}$ for each $i=1, \cdots, n$, and let $\varphi$ be a function of type $\beta_{1} * \cdots * \alpha * \cdots * \beta_{n} \rightarrow \alpha$. The function $\hat{\varphi}$ of type Nat $*\left(\beta_{1} *\right.$ $\left.\cdots * \alpha * \cdots * \beta_{n}\right) \rightarrow \alpha$ is defined by:

$$
\begin{aligned}
\hat{\varphi}\left(s(k),\left(y_{1}, \cdots, x, \cdots, y_{n}\right)\right) & =\varphi\left(y_{1}, \cdots, \hat{\varphi}\left(k,\left(y_{1}, \cdots, x, \cdots, y_{n}\right)\right), \cdots, y_{n}\right) \\
\hat{\varphi}\left(0,\left(y_{1}, \cdots, x, \cdots, y_{n}\right)\right) & =x
\end{aligned}
$$

## Proposition 1

$$
\left.\hat{\varphi}\left(k,\left(y_{1}, \cdots, \varphi\left(y_{1}, \cdots, y, \cdots, y_{n}\right), \cdots, y_{n}\right)=\varphi\left(y_{1}, \cdots, \hat{\varphi}\left(k, y_{1}, \cdots, y, \cdots, y_{n}\right)\right), \cdots, y_{n}\right)\right)
$$

Proof: By induction on $k$.
An immediate consequence of Definition 1 is

$$
\hat{\varphi}(1, x)=\varphi(x)
$$

where $x: \beta_{1} * \cdots * \alpha * \cdots * \beta_{n}$.
Having made the iteration structure of functions explicit, the next theorem helps program transformations exploit that structure. To simplify the exposition, consider the case in which $\varphi: \alpha \rightarrow \alpha$. In this case $\hat{\varphi}:$ Nat $* \alpha \rightarrow \alpha$ and $\hat{\varphi}(k, n)=\varphi^{k}(x)$, where $\varphi^{k}$ denotes $k$ applications of $\varphi$. Suppose now that $f: N a t * N a t \rightarrow \alpha$ satisfies the equation: $f(s(i), s(n))=\varphi(f(i, n))$; then $f(4,7)=\varphi^{4}(f(0,3))=\hat{\varphi}(4, f(0,3))$. More generally, $f(i+k, n+k)=\hat{\varphi}(k, f(i, n))$, which is the result expressed by Theorem 1.

Theorem 1 Assume $f$ of type $N a t^{n} \rightarrow \alpha$, let $y_{i}$ be a term of type $\beta_{i}$ for each $i=1, \cdots, n$, and let $\varphi$ be a function of type $\beta_{1} * \cdots * \alpha * \cdots * \beta_{n} \rightarrow \alpha$. The following are equivalent:

1. $f\left(s\left(x_{1}\right), \cdots, s\left(x_{n}\right)\right)=\varphi\left(y_{1}, \cdots, f\left(x_{1}, \cdots, x_{n}\right), \cdots, y_{m}\right)$
2. $\hat{\varphi}\left(k,\left(y_{1}, \cdots, f\left(x_{1}, \cdots, x_{n}\right), \cdots, y_{n}\right)\right)=f\left(x_{1}+k, \cdots, x_{n}+k\right)$

Proof: That 1 implies 2 is obvious by instantiating $k$ to 1 . The converse is proved by induction on $k$.

To apply this theorem to equation (5), let $M w p O(x)$ be $M w p(0, x)$ and introduce the equation:

$$
\widehat{M u p} O(k, \sigma(i, n)))=\sigma(i+k, n+k)
$$

This gives the equational definition of $\sigma(i, n)$ :

$$
\begin{aligned}
& \sigma(s(i)+k, k)=\widehat{M w p} O(k, u n i t(0)) \\
& \sigma(k, k)=\widehat{M w p} O(k, \operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1)))) \\
& \sigma(k, s(n)+k)=\widehat{M w p} 0(k, u n i t(n))
\end{aligned}
$$

This definition is equivalent to the program below, which is of the form described at the beginning of this section:

$$
\begin{aligned}
\sigma(i, n)= & \text { if } i>n \text { then } e_{1} \\
& \text { else if } i=n \text { then } e_{2} \\
& \text { else } e_{3}
\end{aligned}
$$

where

$$
\begin{aligned}
& e_{1}=\widehat{M w p} O(n, u n i t(0)) \\
& e_{2}=\widehat{M w p} O(i, \operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1)))) \\
& e_{3}=\widehat{M w p} O(i, \operatorname{unit}(n-i-1))
\end{aligned}
$$

### 6.2 Second transformation step

The second transformation step transforms the expressions $e_{1}, e_{2}$ and $e_{3}$. The definition of $\widehat{M w p} 0$ of type $T e r m \rightarrow T e r m$, obtained by Definition 1 , refers to the (inefficient) function Mwp0. To get an efficient program an alternative (but equivalent) definition of $\widehat{M w p} 0$ that does not refer to $M w p 0$ must be generated. Theorem 2 addresses this issue.

To introduce Theorem 2, consider the function upto. Informally, upto $(i, n)=[i, i+1, \cdots, n]$. The function upto satisfies the equation upto $(s(i), s(n))=$ map $s$ upto $(i, n)$. Let map_s be the specialization of the definition of map by $s$ :

$$
\begin{aligned}
& \text { map_s }[]=[] \\
& \text { map_s } x:: x s=s(x)::(\text { map_s } x s)
\end{aligned}
$$

The operators [] and :: are the constructors of the data type List $(\alpha)$. By Theorem 1,

$$
(\widehat{\text { map_s }})(k, u p t o(i, n))=(\text { map_s })^{k}(u p t o(i, n))=u p t o(i+k, n+k)
$$

Theorem 2 will yield the following recursive definition of (map_s) ${ }^{k}$, (that is of $\widehat{m a p} s$ ); it does not refer to map_s.

$$
\begin{aligned}
& \left(\text { map_s }^{k}\right)^{k}[]=[] \\
& \left(\text { map_s }^{k} x:: x s=s^{k}(x)::\left(\left(\text { map_s }^{k} x s\right)\right.\right.
\end{aligned}
$$

Note, in this definition (map_s) ${ }^{k}$ is the function being defined. It is to be regarded atomically; map_s is neither defined nor referred to.

Theorem 2 Let $y_{i}$ be a term of type $\beta_{i}$ for each $i=1, \cdots, n$, let $\varphi$ be a function of type $\beta_{1} * \cdots * \alpha * \cdots * \beta_{n} \rightarrow \alpha$, and let $C$ be a constructor of type $\alpha$. The following are equivalent:

1. $\varphi\left(y_{1}, \cdots, C\left(x_{1}, \cdots, x_{n}\right), \cdots, y_{n}\right)=C\left(\varphi_{1}\left(x_{1}\right), \cdots, \varphi_{n}\left(x_{n}\right)\right)$
2. $\hat{\varphi}\left(k,\left(y_{1}, \cdots, C\left(x_{1}, \cdots, x_{n}\right), \cdots, y_{n}\right)\right)=C\left(\widehat{\varphi_{1}}\left(k, x_{1}\right), \cdots, \widehat{\varphi_{n}}\left(k, x_{n}\right)\right)$

Proof: That 1 implies 2 is obvious by instanciating $k$ to 1 . The converse is proved by induction on $k$.

If C is a constructor of arity zero, Theorem 2 degenerates to the two equations $\varphi\left(y_{1}, \cdots, C, \cdots, y_{n}\right)=$ $C$ and $\hat{\varphi}\left(k,\left(y_{1}, \cdots, C, \cdots, y_{n}\right)\right)=C$.

To apply this result to $\widehat{M w p} 0$, recall that $M w p O(x)=M w p(0, x)$ and that:

$$
\begin{array}{ll}
\operatorname{Mwp}(i, \operatorname{Var}(n)) & =\operatorname{Var}(f(i, n)) \\
\operatorname{Mwp}(i, \operatorname{Abs}(t)) & =\operatorname{Abs}(\operatorname{Mwp}(s(i), t)) \\
\operatorname{Mwp}\left(i, \operatorname{App}\left(t, t^{\prime}\right)\right) & =\operatorname{App}\left(\operatorname{Mwp}(i, t), \operatorname{Mwp}\left(i, t^{\prime}\right)\right)
\end{array}
$$

Introduction of the specializations $f_{0}(x)=f(0, x)$, and $\operatorname{Mwp} 1(x)=\operatorname{Mwp}(1, x)$ allows the application of Theorem 2, producing:

$$
\begin{aligned}
& \widehat{M w p} O(k, \operatorname{Var}(n))=\operatorname{Var}\left(\widehat{f_{0}}(k, n)\right) \\
& \widehat{M w p} O(k, A b s(t))=\operatorname{Abs}(\widehat{M w p} 1(k, t)) \\
& \widehat{M w p} O(k, A p p(s, t))=\operatorname{App}(\widehat{M w p} O(k, s), \widehat{M w p} O(k, t)) .
\end{aligned}
$$

It is easy to show that $\widehat{f_{0}}=\hat{s}$ because $f(0, x)=s(x)$, and that $\hat{s}(k, a)=a+k$ by induction on $k$. Therefore

$$
\begin{aligned}
\widehat{\operatorname{Mwp}} 0(k, \operatorname{Var}(n)) & =\operatorname{Var}\left(\widehat{f_{0}}(k, n)\right) \\
& =\operatorname{Var}(\hat{s}(k, n)) \\
& =\operatorname{Var}(n+k) .
\end{aligned}
$$

Although this appears to have progressed, it is incomplete because $\widehat{M w p} 1$ is still defined in terms of $M w p 1$. Attempts to define $\widehat{M w p} 1$ by this method, however, will require the function $\widehat{M w p} 2$; this would continue forever. Fortunately, there is another way in which Theorem 1 may be applied to equation (5), yielding the equation:

$$
\widehat{M w} p(k,(0, \sigma(i, n)))=\sigma(i+k, n+k)
$$

Applying the same transformation as above produces:

$$
\begin{aligned}
\sigma(i, n)= & \text { if } i>n \text { then } e_{1} \\
& \text { else if } i=n \text { then } e_{2} \\
& \text { else } e_{3}
\end{aligned}
$$

where

$$
\begin{aligned}
& e_{1}=\operatorname{unit}(n) \\
& e_{2}=\widehat{\operatorname{Mwp}}(i,(0, \operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1))))) \\
& e_{3}=\operatorname{unit}(n-1) .
\end{aligned}
$$

Application of Theorem 2 produces a recursive definition of $\widehat{M w p}$ that does not refer to $M w p$ :

$$
\begin{align*}
& \widehat{M w p}(k,(i, \operatorname{Var}(n)))=\operatorname{Var}(\widehat{f}(k,(i, n)))  \tag{8}\\
& \widehat{\operatorname{Mw} p}(k,(i, \operatorname{App}(s, t)))=\operatorname{App}(\widehat{\operatorname{Mw} p}(k,(i, s)), \widehat{\operatorname{Mw}}(k,(i, t))) \\
& \widehat{M w p}(k,(i, \operatorname{Abs}(t)))=\operatorname{Abs}(\widehat{\operatorname{Mw} p}(k,(s(i), t)))
\end{align*}
$$

The transformation is not yet finished. Equation (8) remains to be improved by finding a recursive definition of $\hat{f}$ that does not refer to the function $f$.

### 6.3 Transformation of $\hat{f}$

Recall the equations for $f$ :

$$
\begin{align*}
& f(0, n)=s(n)  \tag{9}\\
& f(s(i), 0)=0  \tag{10}\\
& f(s(i), s(n))=s(f(i, n)) \tag{11}
\end{align*}
$$

Applying Theorem 2 to equation (11) yields:

$$
\begin{equation*}
\hat{f}(k,(s(i), s(n)))=s(\hat{f}(k,(i, n))) \tag{12}
\end{equation*}
$$

This suggests attempting a conditional definition for $\hat{f}$. Using equations (9), (10), (11), Theorem 2, Theorem 1, and Definition 1 produces:

$$
\begin{align*}
& \hat{f}(k,(0, s(n)))=s(\hat{s}(k, n))=s(n+k)  \tag{13}\\
& \hat{f}(k,(s(i), 0))=0  \tag{14}\\
& \hat{f}(k,(0,0))=k \tag{15}
\end{align*}
$$

Applying Theorem 1 to Equation (12) gives:

$$
\begin{aligned}
\hat{f}(k,(i+p, n+p)) & =\hat{s}(p, \hat{f}(k,(i, n))) \\
& =\hat{f}(k,(i, n))+p .
\end{aligned}
$$

Applying that to equations (13), (14), (15) produces

$$
\begin{aligned}
& \hat{f}(k,(s(i)+p, p))=p \\
& \hat{f}(k,(p, s(n)+p))=n+1+k+p \\
& \hat{f}(k,(p, p))=k+p
\end{aligned}
$$

This equational definition is equivalent to the program:

$$
\begin{aligned}
\hat{f}(k,(i, n))= & \text { if } i>n \text { then } n \\
& \text { else if } i=n \text { then } n+k \\
& \text { else } n+k
\end{aligned}
$$

```
fun apply_substitution_ \(\sigma_{0}(M)\)
=
    let fun
        \(\widehat{M w p}(k,(i, \operatorname{Var}(n))) \quad=\) if \(i>n\) then \(\operatorname{Var}(n)\) else \(\operatorname{Var}(n+k)\)
        \(\mid \widehat{M w p}(k,(i, A b s(t)))=A b s(\widehat{M w p}(k,(s(i), t)))\)
        \(\mid \widehat{M w p}\left(k,\left(i, \operatorname{App}\left(t, t^{\prime}\right)\right)\right)=\operatorname{App}\left(\widehat{M w p}(k,(i, t)), \widehat{M w p}\left(k,\left(i, t^{\prime}\right)\right)\right)\)
        fun
        \(\sigma(i, n) \quad=\) if \(i>n\) then \(\operatorname{unit}(n)\)
    else if \(i=n\) then \(\widehat{\operatorname{Mwp}}(i,(0, \operatorname{Abs}(\operatorname{App}(\operatorname{Var}(0), \operatorname{Var}(1)))))\)
    else \(\operatorname{unit}(n-1)\)
        fun
        \(\operatorname{Ewp}(i, \operatorname{Var}(n)) \quad=\sigma(i, n)\)
        \(\mid \operatorname{Ewp}(i, A b s(t))=\operatorname{Abs}(\operatorname{Ewp}(s(i), t))\)
        \(\mid \operatorname{Ewp}\left(i, \operatorname{App}\left(t, t^{\prime}\right)\right)=\operatorname{App}\left(E w p(i, t), \operatorname{Ewp}\left(i, t^{\prime}\right)\right)\)
    in \(\operatorname{Ewp}(0, M)\) )
    end
```

Figure 7: Final result

The program simplifies to:

$$
\hat{f}(k,(i, n))=\text { if } i>n \text { then } n \text { else } n+k
$$

By unfolding $\hat{f}$ and by a well known property of if $\cdots$ then $\cdots$ else $\cdots$, equation (8) becomes:

$$
\widehat{M w p}(k,(i, \operatorname{Var}(n)))=\text { if } i>n \text { then } \operatorname{Var}(n) \text { else } \operatorname{Var}(n+k)
$$

Including the transformed form of $\sigma$, which comes from above, produces the program in Figure 7 which does not perform redundant computations for $\sigma_{i}$ and $f_{i}$. The transformation involved in this section has been done manually. However the transformation process is systematic and involves equational reasoning using Theorem 1 and Theorem 2 . It shows implicitly how to automatically transform a function of type Nat $* N a t \rightarrow$ Nat into a more efficient conditional form.

## 7 Directions

The paper has presented a clearly motivated and correct specification for a subtle representation of $\lambda$-terms, the implementation of which has, in the second authors experience, been prone to
"off by one errors." It has taken this abstract specification, with its extensive use of higherorder concepts, reduced it to a first-order program, introduced index arithmetic and produced an efficient algorithm that exploits computer arithmetic.

This development illustrates several new techniques. First, it makes the monadic structure in the development of the specification explicit by showing that it is a monad in FunSeq. It supports this structure with new program transformation techniques which allow the implicit use of arithmetic to be "rediscovered" formally. Finally, it demonstrates the feasibility of integrating tools for monadic programming and specification, which tend to be higher-order, with relatively standard program transformation technology, which is strictly first-order. The importance of partial evaluation technology in bridging this gap cannot be overstated.

### 7.1 Technology

Currently our technology is a tower of Babble. Automatic support for monadic programming, including automatic program generation, exists in TRPL, a language developed by Sheard[9,5]. Hook uses Standard ML for examples of monadic program development because its module system is the most able to express the structure of the monads. The partial evaluator, Schism, uses its own (typed) dialect of Scheme as its object language. ASTRE, Bellegarde's program transformation system, is written in CAML. It uses a very simple first-order language as its object language.

In this environment, claims that the development is automatable mean that we have automated the process "piecewise", translating between the formalisms in a nearly mechanical fashion. It is, of course, our vision that one day these tools will all work in concert, allowing a development to proceed from specification to efficient realization with human intervention only when necessary.

### 7.2 Reuse

Although this paper has focused on the $\lambda$-calculus, the specification can be applied to virtually any abstract syntax with a regular binding structure provided its type can be expressed as a monad and the appropriate definition of map_with_policy can be given. For example, adding boolean constants and a conditional has no effect on the specification of substitution and only changes map_with_policy by defining it to apply $f$ recursively on the components of the conditional without applying $Z$. Adding let is also trivial; again, no changes need to be made to the specification of substitution-only to map_with_policy. In this case, map_with_policy must apply $Z$ to $f$ when it enters the component in which the bound variable has been introduced. This ability to reuse specifications is one of the strongest arguments for the adoption of monads as a tool to structure program specification and development.

But what about the transformations? Can we reuse program improvements? Here we have less experience, however the decisions that are required to improve programs for the different scenarios outlined above are substantially the same. It appears that a transformation system that records its development may be able to replay the development and obtain similar improvements.

### 7.3 Application to more complex types

In earlier work more complicated types have been investigated. In particular, the following version of the Term type, which allows for a standard representation of variable names, was used:

$$
\begin{array}{ll}
\text { datatype } \operatorname{Term}(\alpha, \beta)= & \operatorname{Var}(\alpha) \\
& \operatorname{Abs}(\beta, \operatorname{Term}(\alpha)) \\
& \operatorname{App}(\operatorname{Term}(\alpha, \beta) * \operatorname{Term}(\alpha, \beta))
\end{array}
$$

In this representation $\lambda x . x$ would be represented

$$
A b s(\mathbf{x}, \operatorname{Var}(\mathbf{x}))
$$

The techniques presented here all apply to this more general case, but the explanations are somewhat more involved. For example, instead of using a category where morphisms are sequences of functions indexed by numbers, a category of trees of functions indexed by sequences of elements from an arbitrary type must be used. Similarly, the data types introduced to encode the higher-order function applications become more complex.

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[^0]:    *Submitted to the Colloquium on Formal Approaches of Software Engineering, 1993.
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    ${ }^{\ddagger}$ Both authors are supported in part by a grant from the NSF (CCR-9101721).

[^1]:    ${ }^{1}$ The coercion of numbers to terms implicit here will become explicit in the programs developed below.

[^2]:    ${ }^{2}$ This is a simplified form of the Term data type in Hook, Kieburtz and Sheard[5].

[^3]:    ${ }^{3}$ The constructors for the data type Nat are 0 and $s$, i.e. datatype Nat $=0 \mid s($ Nat $)$.

[^4]:    ${ }^{4}$ This composition is often called the Kleisli star or natural extension. Ewp is a mnemonic for extension with policy.

